

Integrated scheduling of maintenance and transportation operations in military supply chains

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(this work was done with **Dmitry Tsadikovich** and **Hanan Tell** (BIU))



Outline

This talk will be around the following issues:

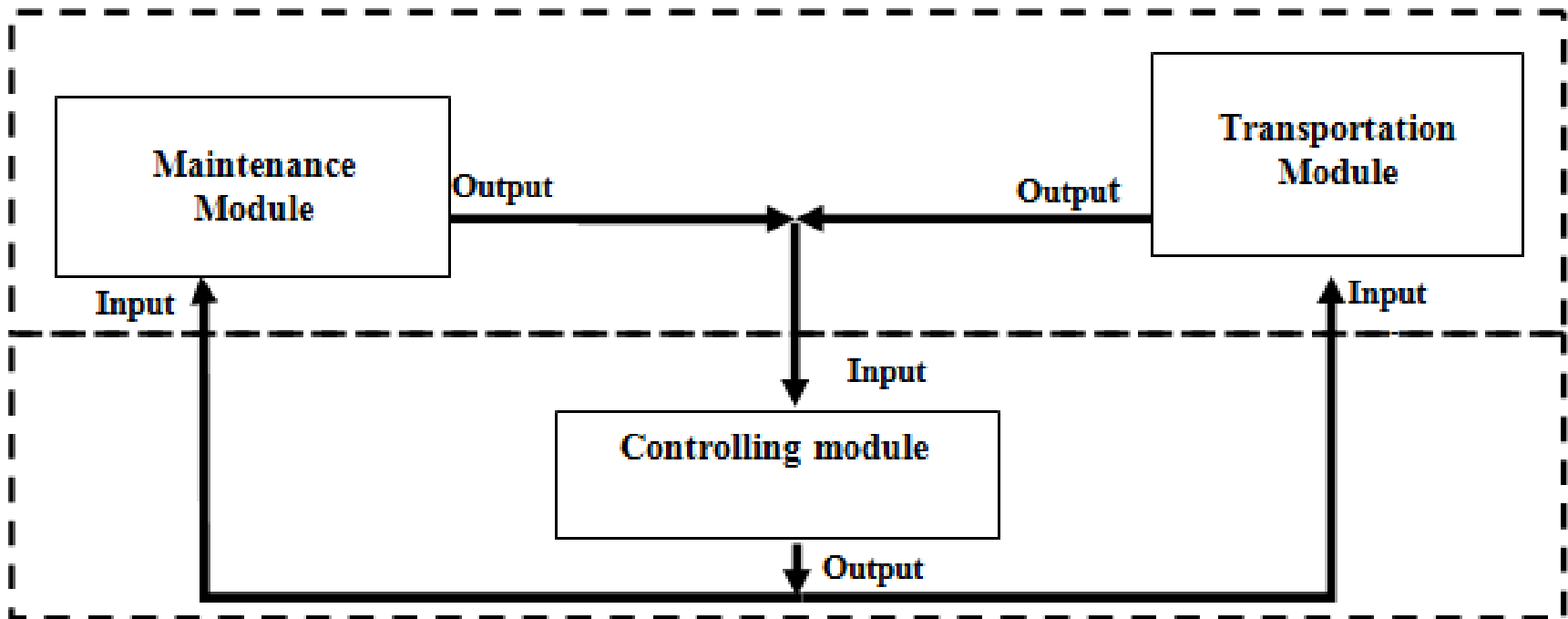
- Modeling the maintenance module (MM) and transportation module (TM) in MSC
- Design of the iterative local-search procedure proved to be more efficient than the standard GAMS/CPLEX solver



A military supply chain has the following linked activities:

- procurement,
- production,
- packaging,
- warehousing,
- repair,
- **maintenance** and
- **transportation** of army supplies.

Interaction between the modules



Model MM

To find $Min \sum_{j=1}^n F_j$ (1)

subject to:

$$Y_{i'j} - Y_{ij} \geq p_{ij} - U_{ij}, \text{ for all } (i, j) \rightarrow (i', j) \in A \quad (2)$$

$$Y_{ij} - Y_{ij'} \geq p_{ij'} - U_{ij'} \text{ or } Y_{ij'} - Y_{ij} \geq p_{ij}, \text{ for all } (i, j') \text{ and } (i, j), i = 1, 2, \dots, m, j = 1, 2, \dots, n \quad (3)$$

$$\sum_{i \in L_{j, k(j)}} B_{ij, k(j)} = 1, \text{ for all } L = \{L_{j, k(j)}\}, j = 1, 2, \dots, n, k(j) = 1, 2, \dots, K_j \quad (4)$$

$$F_j \leq D_j, \text{ for all } j = 1, 2, \dots, n \quad (5)$$

$$Y_{ij} \geq 0, \text{ for all } (i, j) \in N \quad (6)$$

$$B_{ij, k(j)} \in \{0, 1\}, \text{ for all } i = 1, 2, \dots, m, j = 1, 2, \dots, n, k(j) = 1, 2, \dots, K_j \quad (7)$$

Model TM

$$\text{To find } \text{Min} \quad \frac{1}{S} \sum_{(a,b) \in E} (t_{ab} - W_{ab}) x_{ab} \quad (8)$$

subject to:

$$\sum_{b \in \mathfrak{R}} x_{0b} = S \quad (9)$$

$$\sum_{a \in \mathfrak{R}} x_{a0} = \sum_{b \in \mathfrak{R}} x_{0b} \quad (10)$$

$$\sum_{b \in \mathfrak{R}} x_{ab} = 1, \forall a \in \mathfrak{R} \quad (11)$$

$$\sum_{b \in \mathfrak{R}} x_{ba} = 1, \forall a \in \mathfrak{R} \quad (12)$$

$$z_{ab} \leq x_{ab}, \forall (a,b) \in E \quad (13)$$

$$\sum_{(a,b) \in E} z_{ab} \leq S_{con} \quad (14)$$

$$s_a + t_a^u + (t_{ab} - W_{ab}) - \Delta t_{ab} z_{ab} - s_b \leq M * (1 - x_{ab}), \quad \forall (a,b) \in I \cup (\{0\} \times \mathfrak{R}) \quad (15)$$

$$u_a \leq s_a + t_a^u \leq r_a, \forall a \in \mathfrak{R} \quad (16)$$

$$0 \leq y_a \leq C, \forall a \in \mathfrak{R} \quad (17)$$

$$y_a + q_a - y_b \leq M * (1 - x_{ab}), \forall (i,j) \in I \cup (\{0\} \times \mathfrak{R}) \quad (18)$$

$$s_a, y_a \geq 0, \forall a \in \mathfrak{R} \quad (19)$$

Model CM

Problem CM.

$$\text{To find } \text{Min } P = F_{TR}(W_{ab}) - F_{MM}(U_{ij}) \quad (21)$$

where

$$F_{TR}(W_{ab}) = \sum_{(a,b) \in E} (t_{ab} - W_{ab}) + \sum_{a \in \mathcal{R}} t_a^u, \text{ and } F_{MM}(U_{ij}) = \sum_{i=1}^m \sum_{j=1}^n (Y_{ij} + p_{ij} - U_{ij}), \quad (22)$$

subject to:

$$\sum_{(a,b) \in E} W_{ab} \leq \alpha_1 \quad (23)$$

$$\sum_{i=1}^m \sum_{j=1}^n U_{ij} \leq \alpha_2 \quad (24)$$

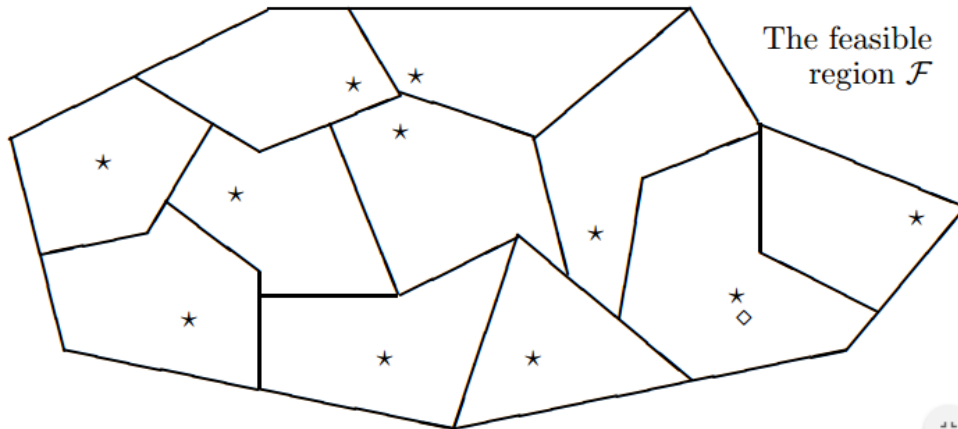
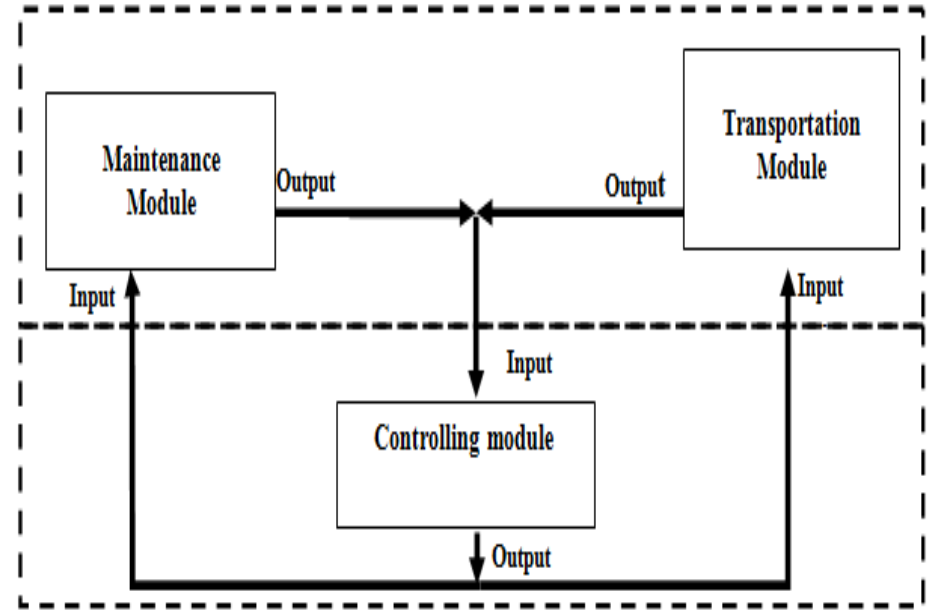
$$W_{ab} \geq s_b - r_b \quad (25)$$

$$\sum_{j=1}^n Q_{jk}^a \leq C, \text{ for } k = 1, \dots, S, a = 1, \dots, \mathcal{R} \quad (26)$$

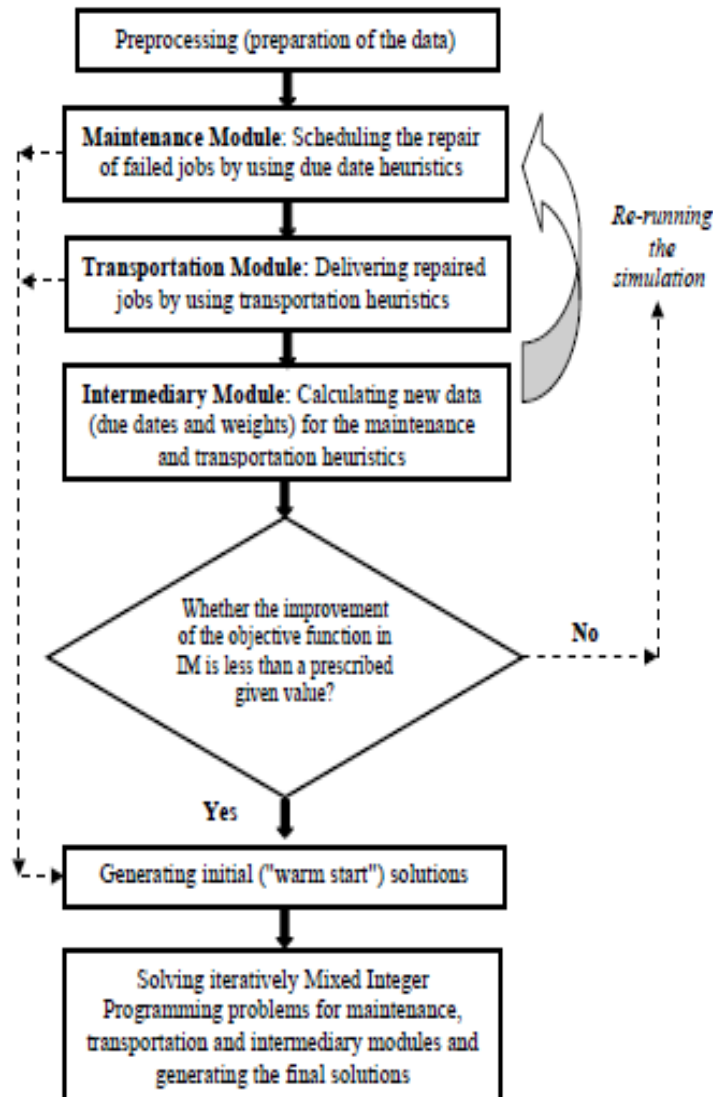
$$\sum_{k=1}^S Q_{jk}^a = TQ_j^a, \text{ for } j = 1, \dots, n, a = 1, \dots, \mathcal{R} \quad (27)$$

$$t_a^u = \beta \sum_{k=1}^S \sum_{j=1}^n Q_{jk}^a, \text{ for } a = 1, \dots, \mathcal{R} \quad (28)$$

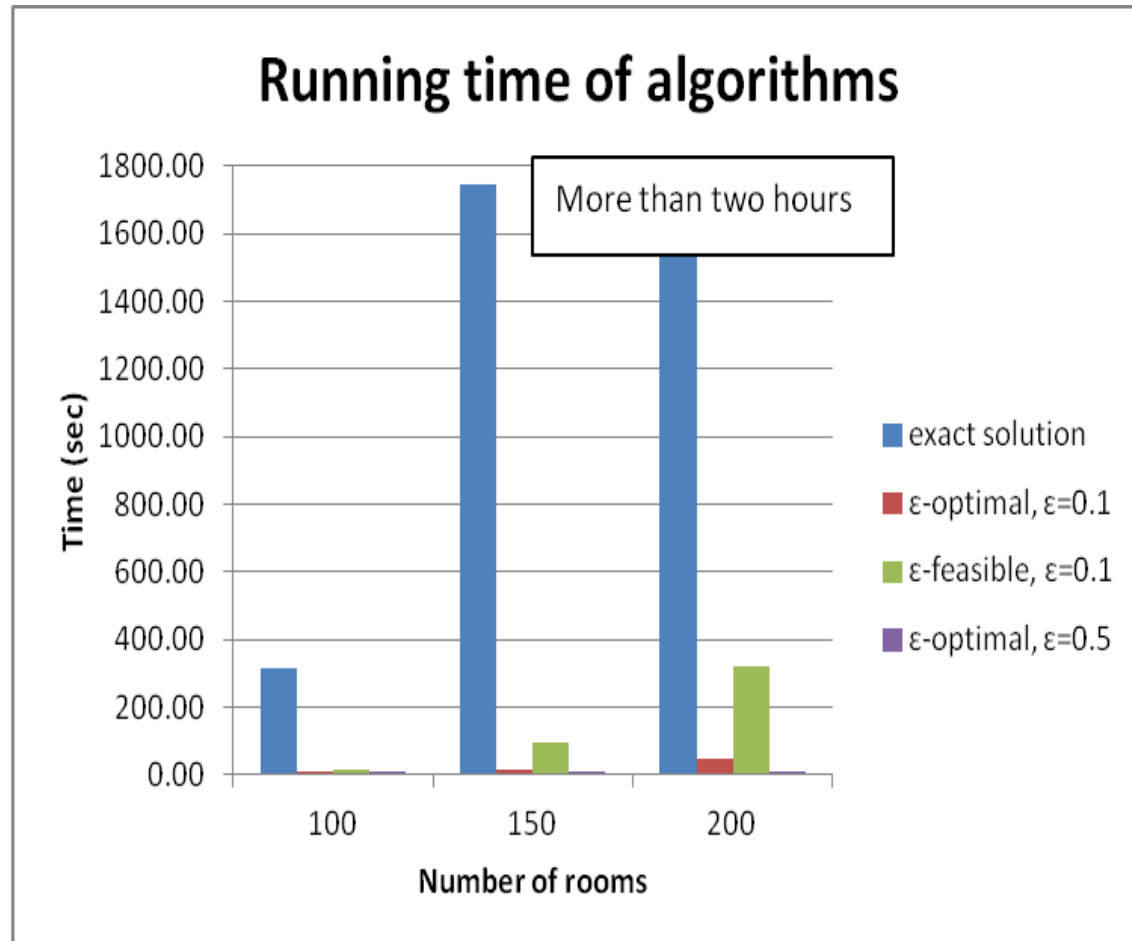
Idea of Decomposition and Control



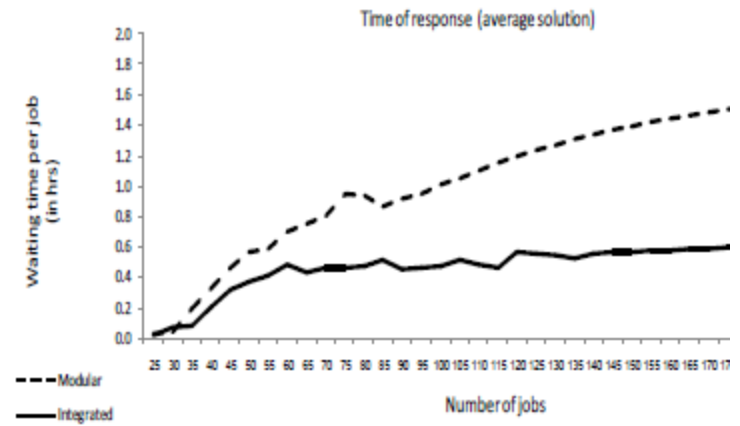
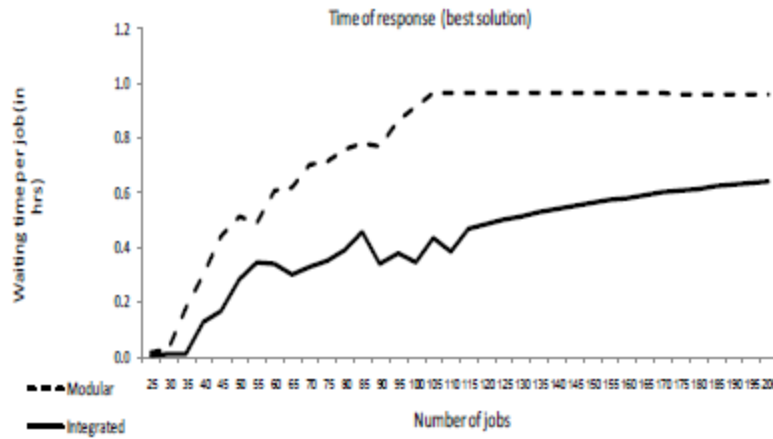
Flowchart of the algorithm



Computational results: Computing time



Computational results: Time of response



Computational results: Military effectiveness

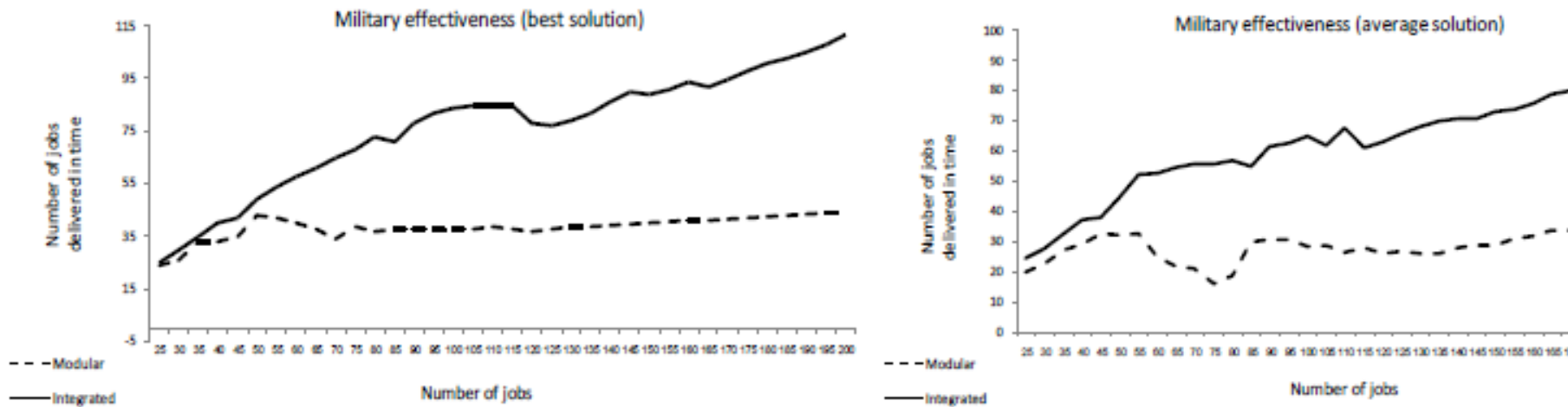


Fig. 5. The military effectiveness measure as a function of the number of jobs.



Conclusion

- A new general framework for improving the computational process of coordinating MSC is applicable for many other SCM problems.
- Further development of new, highly-efficient decomposition methods is possible for other types of problems like lot-sizing, allocation, etc.
- Stochastic and multi-dimensional procedures are of especial interest for future research.



• Bibliography

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Thank you!